

Description

The μPD42505 is a 5048-word by 8-bit dual-port line buffer fabricated with a silicon-gate CMOS process. The device is capable of asynchronous read and write operation at high speed, and can be used as a time axis converter or a digital delay line of up to 5048 bits (10 bits minimum at maximum frequency).

Applications include image processing in facsimile machines, plain paper copiers, video systems, and other optical scanners; time base correction in video playback systems; and data communication buffering in multiprocessor systems and local area networks.

Features

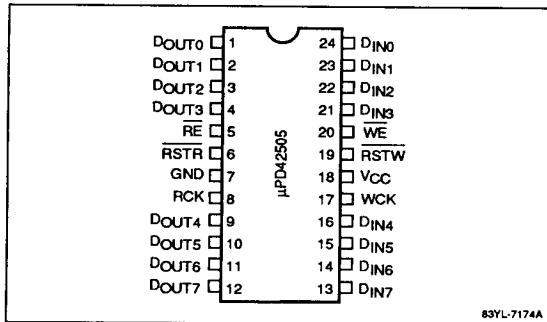
- 5048-word x 8-bit organization
- Dual-port operation
- Image processing and data communications applications
- Asynchronous and simultaneous reading/writing
- 1H (5048-bit) delay line capability
- TTL-compatible inputs and outputs
- Three-state outputs
- Single + 5-volt power supply
- 24-pin plastic DIP and 28-pin plastic ZIP packaging

Pin Identification

Symbol	Function
D _{IN0} - D _{IN7}	Write data inputs
D _{OUT0} - D _{OUT7}	Read data outputs
RCK	Read clock input
RE	Read enable input
RSTR	Read address reset input
RSTW	Write address reset input
WCK	Write clock input
WE	Write enable input
GND	Ground
V _{CC}	+5-volt power supply

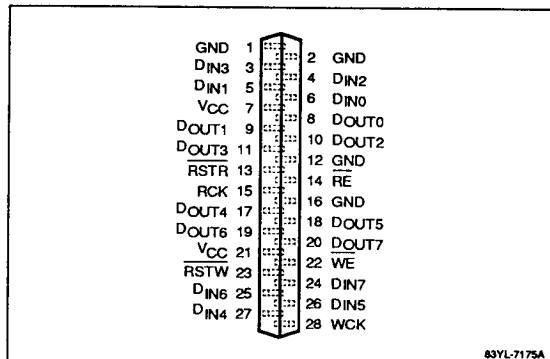
Pin Configurations

24-Pin Plastic DIP

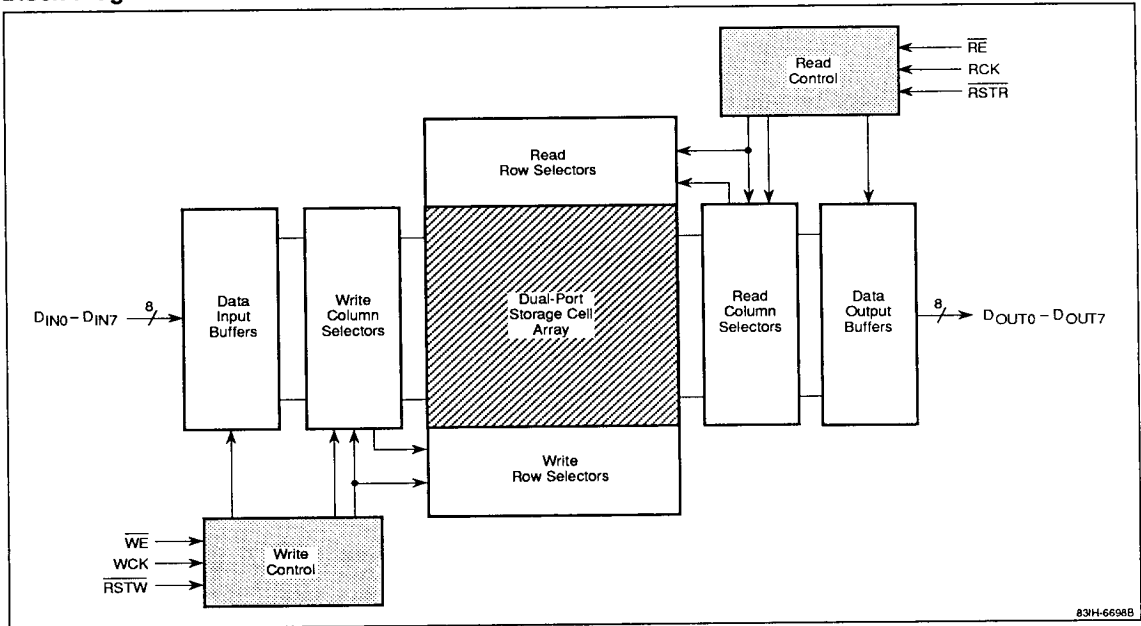


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28-Pin Plastic ZIP



Block Diagram



Ordering Information

Device	Cycle Time (min)	Read Access Time (max)	Hold Time (min)	Package
μPD42505C-50	50 ns	40 ns	5 ms	24-pin plastic DIP
C-75	75 ns	55 ns		
C-50H	50 ns	40 ns	20 ms	
C-75H	75 ns	55 ns		
μPD42505V-50	50 ns	40 ns	5 ms	28-pin plastic ZIP
V-75	75 ns	55 ns		
V-50H	50 ns	40 ns	20 ms	
V-75H	75 ns	55 ns		

Pin Functions

DIN₀ through DIN₇ (Data Inputs). New data is entered on these pins.

DOUT₀ through DOUT₇ (Data Outputs). These tri-state outputs are used to access stored information. In a simple digital delay line application, a minimum delay of 10 clock cycles is required to move data from the input pins to the output pins.

RCK (Read Clock Input). All read cycle are executed synchronously with RCK. The states of both RSTR and RE are strobed by the rising edge of RCK at the

beginning of a cycle. This same edge of RCK starts internal read operation, and access time is referenced to this edge. The internal read address increments with each RCK cycle, unless RE is high to hold the read address constant. Unless inhibited by RE, the internal read address will automatically wrap around from 5047 to 0 and begin incrementing again.

RE (Read Enable Input). This signal controls read operation. If RE is low, all read cycles proceed. If RE is at a high level, the data outputs become high impedance and the internal read address stops incrementing. The state of RE is strobed by the rising edge of RCK.

RSTR (Read Address Reset Input). This signal is strobed by the rising edge of RCK and resets the internal read address to 0.

RSTW (Write Address Reset Input). Bringing this signal low resets the internal write address to 0. The state of this input is strobed by the rising edge of WCK.

WCK (Write Clock Input). All write cycles are executed synchronously with WCK. The states of both RSTW and WE are strobed by the rising edge of WCK at the beginning of a cycle, and the data inputs are strobed by the rising edge of WCK at the end of a cycle. The internal write address increments with each WCK cycle, unless WE is at a high level to hold the write address constant. Unless inhibited by WE, the internal write address will automatically wrap around from 5047 to 0 and begin incrementing again.

WE (Write Enable Input). This input is similar to RE but controls write operation. If WE is at a high level, no data is written to storage cells and the write address does not increment. The state of WE is strobed by the rising edge of WCK.

Operation

Reset Cycle. The μPD42505 requires the initialization of internal circuits using the RSTW/RSTR reset signals before starting operation as a time axis converter or a digital delay line.

A reset cycle can be executed at any time and does not depend on the state of RE or WE. However, RSTW and RSTR must satisfy required setup and hold times as measured from the rising edges of WCK and RCK.

Write/Read Cycles. Write and read cycles are synchronized to their respective WCK/RCK inputs and executed individually when WCK or RCK is high and WE or RE is low. Write data must satisfy setup and hold times as specified from the rising edge of WCK. New data written to a particular address is available for reading after 1/2 write cycle + 500 ns (maximum).

The access time of a read cycle is measured from the rising edge of RCK, either by t_{ACR} for an access during the first cycle directly after a reset begins, or by t_{AC} for an access under other conditions. Stored data is read nondestructively; data can be read repeatedly within a prescribed time of 5 ms maximum (20 ms maximum for -H versions).

Time Axis Conversion. To use the μPD42505 as a time axis converter, write and read cycles must be controlled independently. Write and read ports must be initialized

separately using the reset signals. Write cycles can then be executed in synchronization with WCK and write data can be stored sequentially from address 0 of this device. Afterward, when a read cycle is executed in synchronization with RCK, stored data can be read sequentially from address 0.

Since write and read cycles can be executed independently, data loaded at one arbitrary drive frequency can be read at another arbitrary drive frequency. In this sense, the μPD42505 functions as a time axis converter.

Digital Delay Line. The μPD42505 can be easily used as a digital delay line of 5,048 bits or less. After the internal circuits are initialized using simultaneous RSTW/RSTR signals, write/read cycles also may be executed simultaneously by supplying the same pulse to the write (WCK) and read (RCK) clocks. Write data is always read after the full 5,048-bit delay if neither write nor read operation has been inhibited. This is the essential delay line function.

If either WE or RE is set at a nonselected (high) level for several cycles while the other is maintained in a selected (low) level, the delay line length can differ from 5,048 bits.

For example, if only WE is set to a high level (write disable) for a small number of cycles, read cycles are executed continuously and the delay line length is large (see the waveform for "(5048-m)-Bit Delay Line No. 2"). Alternatively, if only RE is set to a high level (read disable) for a small number of cycles, write cycles are executed continuously and the delay line length is small. Note that the minimum delay line length is 10 bits (for maximum frequency operation) and the maximum is 5,048 bits.

A data delay of 5,048 bits or less can also be obtained by applying the RSTW and RSTR signals at different times. For example, data loaded for "m" cycles after RSTW can then be read after supplying RSTR. In this case, since write data can be read from the beginning after a delay of "m" cycles, the device can be used as an "m-bit" digital delay line.

The RSTW/RSTR reset signals can also be simultaneously loaded at every 1H (horizontal line) period. In this case, write data loaded in the previous line cycle is read out from the beginning as read data after the reset. Therefore, a delay line length ranging from 10 to 5,048 bits can be obtained according to the length of the reset signals supplied. Refer to the timing waveform for an "n-Bit Delay Line."

Absolute Maximum Ratings

Supply voltage, V_{CC}	-1.5 to +7.0 V
Voltage on any input pin, V_I	-1.5 to +7.0 V
Voltage on any output pin, V_O	-1.5 to +7.0 V
Short-circuit output current, I_{OS}	20 mA
Operating temperature, T_{OPR}	-20 to +70 °C
Storage temperature, T_{STG}	-55 to +125 °C

Exposure to Absolute Maximum Ratings for extended periods may affect device reliability; exceeding the ratings could cause permanent damage. The device should be operated within the limits specified under DC and AC Characteristics.

Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{CC}	4.5	5.0	5.5	V
Input voltage, high	V_{IH}	2.4		V_{CC}	V
Input voltage, low	V_{IL}	-1.5		0.8	V
Ambient temperature	T_A	-20		70	°C

Capacitance

$T_A = 25^\circ\text{C}; V_{CC} = +5.0\text{ V} \pm 10\%; f = 1\text{ MHz}$

Parameter	Symbol	Max	Unit	Test Conditions
Input capacitance	C_I	5	pF	$\overline{WE}, \overline{RE}, WCK, RCK, RSTW, RSTR, D_{IN0} - D_{IN7}$
Output capacitance	C_O	7	pF	$D_{OUT0} - D_{OUT7}$

Notes:

- (1) These parameters are sampled and not 100% tested.

DC Characteristics

$T_A = -20\text{ to }+70^\circ\text{C}; V_{CC} = +5.0\text{ V} \pm 10\%$

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Write/read cycle operating current	I_{CC}			60	mA	
Input leakage current	I_I	-10		10	μA	$V_I = 0\text{ V to }V_{CC}$; all other pins not under test = 0 V
Output leakage current	I_O	-10		10	μA	D_{OUT} disabled; $V_O = 0\text{ to }5.5\text{ V}$
Output voltage, high	V_{OH}	2.4			V	$I_{OH} = -1\text{ mA}$
Output voltage, low	V_{OL}			0.4	V	$I_{OL} = 2\text{ mA}$

AC Characteristics

$T_A = -20\text{ to }+70^\circ\text{C}; V_{CC} = +5.0\text{ V} \pm 10\%$

Parameter	Symbol	μPD42505-50		μPD42505-75		μPD42505-50H		μPD42505-75H		Unit	Test Conditions
		Min	Max	Min	Max	Min	Max	Min	Max		
Write clock cycle time	t_{WCK}	50	990	75	990	50	3960	75	3960	ns	
WCK pulse width	t_{WCW}	20		30		20		30		ns	
WCK precharge time	t_{WCP}	20		30		20		30		ns	
Read clock cycle time	t_{RCK}	50	990	75	990	50	3960	75	3960	ns	
RCK pulse width	t_{RCW}	20		30		20		30		ns	
RCK precharge time	t_{RCP}	20		30		20		30		ns	
Access time	t_{AC}		40		55		40		55	ns	
Access time after a reset cycle	t_{ACR}		40		55		40		55	ns	
Output hold time	t_{OH}	5		5		5		5		ns	
Output hold time after a reset cycle	t_{OHR}	5		5		5		5		ns	(Note 7)
Output active time	t_{LZ}	5	40	5	55	5	40	5	55	ns	(Note 4)
Output disable time	t_{HZ}	5	40	5	55	5	40	5	55	ns	(Note 4)
Data-in setup time	t_{DS}	15		20		15		20		ns	

AC Characteristics

$T_A = -20$ to $+70^\circ\text{C}$; $V_{CC} = +5.0\text{V} \pm 10\%$

Parameter	Symbol	μPD42505-50		μPD42505-75		μPD42505-50H		μPD42505-75H		Unit	Test Conditions
		Min	Max	Min	Max	Min	Max	Min	Max		
Data-in hold time	t_{DH}	5		5		5		5		ns	
Reset active setup time	t_{RS}	15		20		15		20		ns	(Note 8)
Reset active hold time	t_{RH}	5		5		5		5		ns	(Note 8)
Reset inactive hold time	t_{RN1}	5		5		5		5		ns	(Note 9)
Reset inactive setup time	t_{RN2}	15		20		15		20		ns	(Note 9)
Write enable setup time	t_{WES}	15		20		15		20		ns	(Note 10)
Write enable hold time	t_{WEH}	5		5		5		5		ns	(Note 10)
Write enable high delay from WCK	t_{WEN1}	5		5		5		5		ns	(Note 11)
Write enable low delay to WCK	t_{WEN2}	15		20		15		20		ns	(Note 11)
Read enable setup time	t_{RES}	15		20		15		20		ns	(Note 10)
Read enable hold time	t_{REH}	5		5		5		5		ns	(Note 10)
Read enable high delay from RCK	t_{REN1}	5		5		5		5		ns	(Note 11)
Read enable low delay to RCK	t_{REN2}	15		20		15		20		ns	(Note 11)
Write disable pulse width	t_{WEW}	0		0		0		0		ms	(Note 6)
Read disable pulse width	t_{REW}	0		0		0		0		ms	(Note 6)
Write reset time	t_{RSTW}	0		0		0		0		ms	(Note 6)
Read reset time	t_{RSTR}	0		0		0		0		ms	(Note 6)
Transition time	t_T	3	35	3	35	3	35	3	35	ns	

Notes:

- (1) All voltages are referenced to ground.
- (2) Input pulse rise and fall times assume $t_T = 5$ ns.
- (3) Input pulse levels = GND to 3 V. Transition times are measured between 3 V and 0 V.
- (4) This delay is measured at ± 200 mV from the steady-state voltage with the load specified in figure 2. Under any conditions, $t_{LZ} \geq t_{HZ}$.
- (5) Input timing reference levels = 1.5 V.
- (6) t_{WEW} (max) and t_{REW} (max) must be satisfied by the next equations in one line cycle operation:
 $t_{WEW} + t_{RSTW} + 5048t_{WCK} \leq 5$ ms (20 ms for -H versions)
 $t_{REW} + t_{RSTR} + 5048t_{RCK} \leq 5$ ms (20 ms for -H versions)
- (7) This parameter applies when $t_{RCK} \geq t_{ACR}$ (max)
- (8) If either t_{RS} or t_{RH} is less than the specified value, reset operations are not guaranteed.
- (9) If either t_{RN1} or t_{RN2} is less than the specified value, internal reset operations may extend to cycles immediately preceding or following the period of desired reset operations.
- (10) If either t_{WES} or t_{WEH} (t_{RES} or t_{REH}) is less than the specified value, write (read) disable operations are not guaranteed.
- (11) If either t_{WEN1} or t_{WEN2} (t_{REN1} or t_{REN2}) is less than the specified value, internal write (read) disable operations may extend to cycles immediately preceding or following the period of desired disable operations.

Figure 1. Output Load for t_{AC} , t_{ACR} , t_{OH} , and t_{OHR}

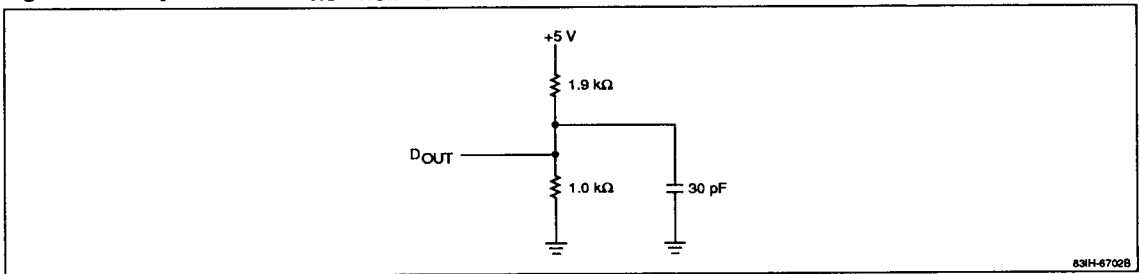


Figure 2. Output Load for t_{LZ} and t_{HZ}

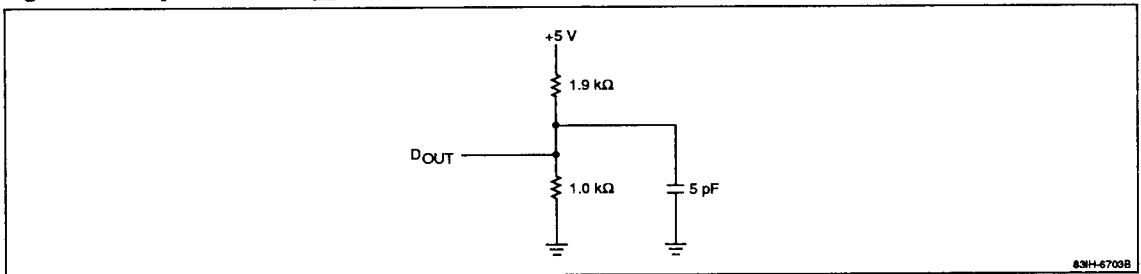


Figure 3. Input Timing

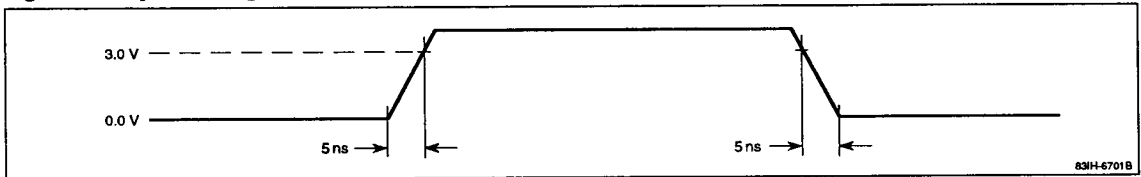
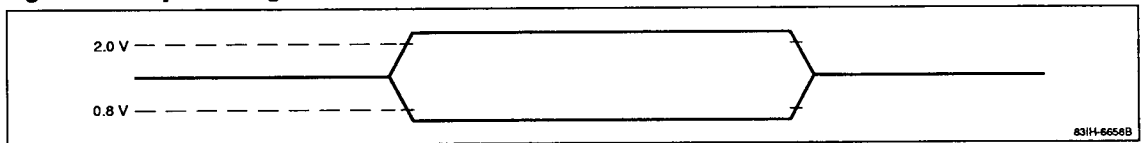
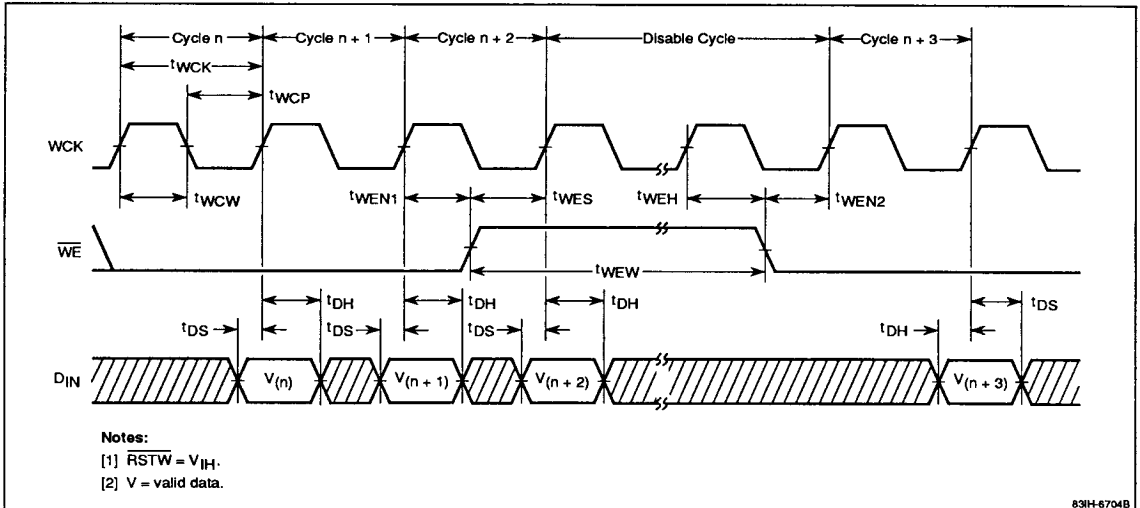


Figure 4. Output Timing



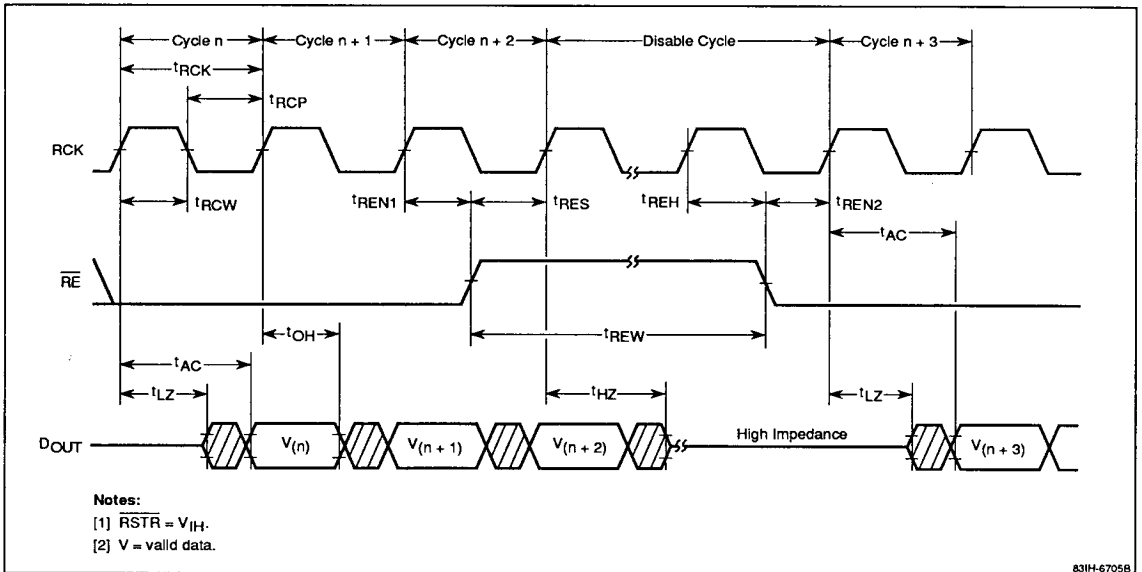
Timing Waveforms

Write Cycle



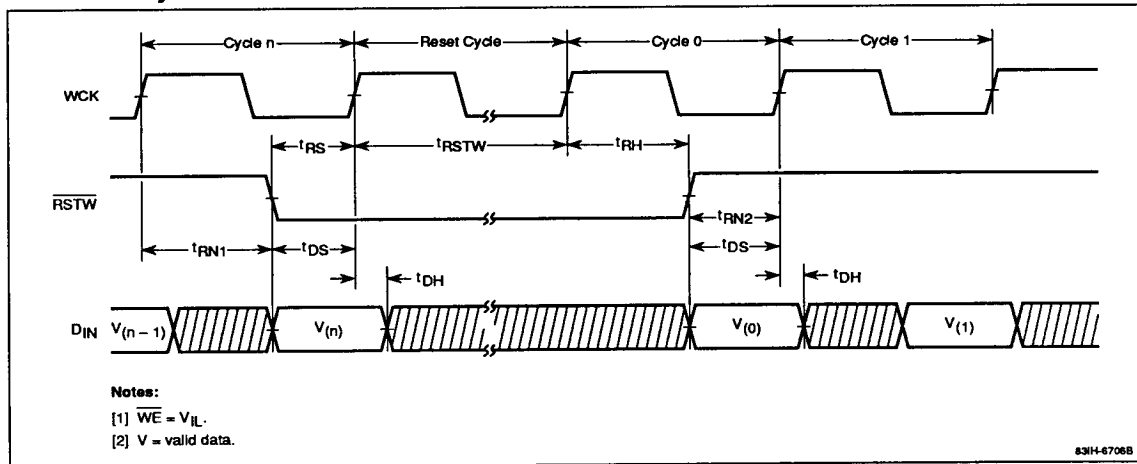
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Read Cycle

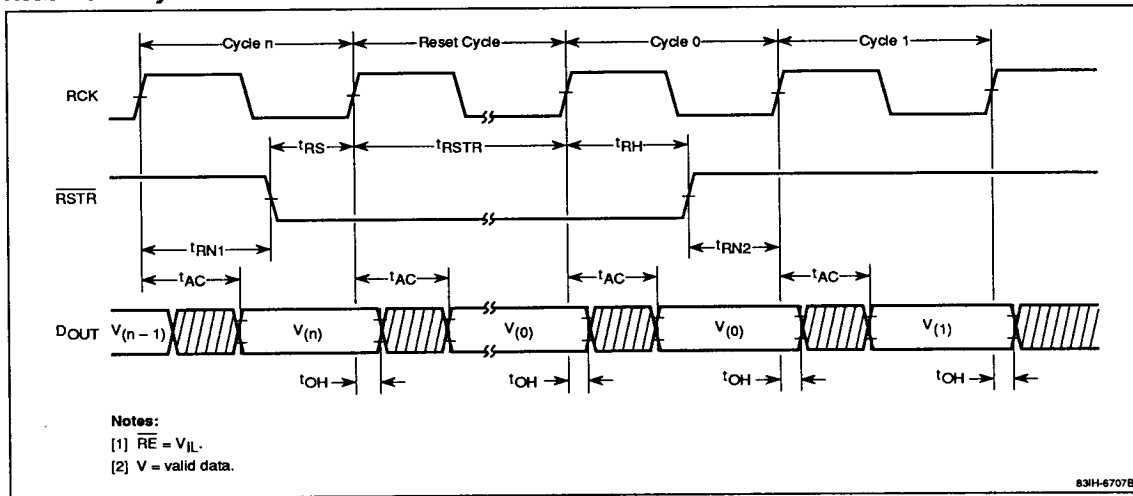


Timing Waveforms (cont)

Write Reset Cycle

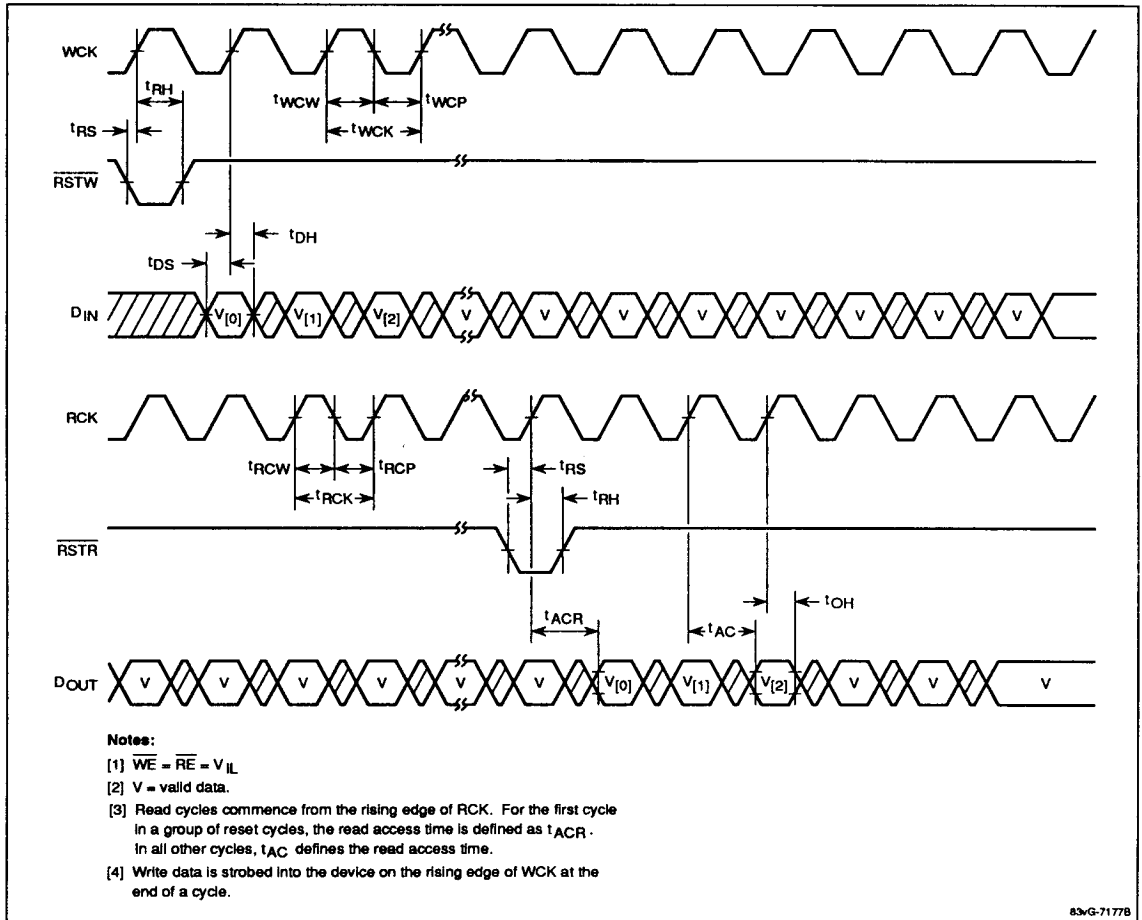


Read Reset Cycle



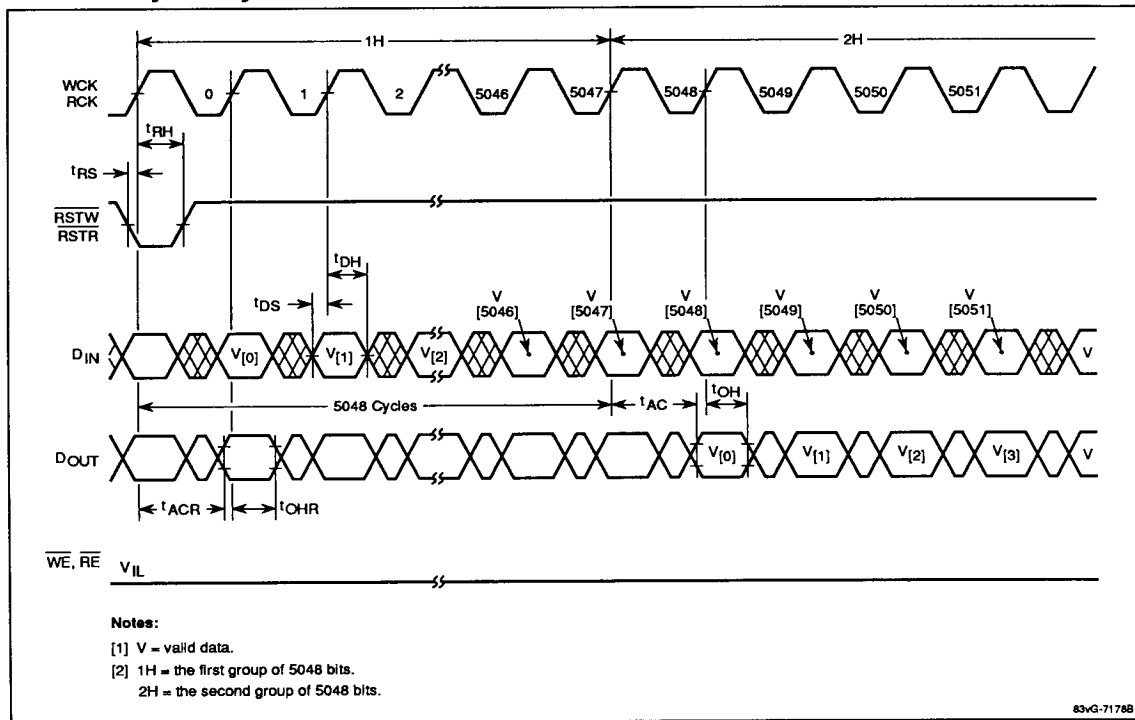
Timing Waveforms (cont)

Time Axis Conversion Cycle



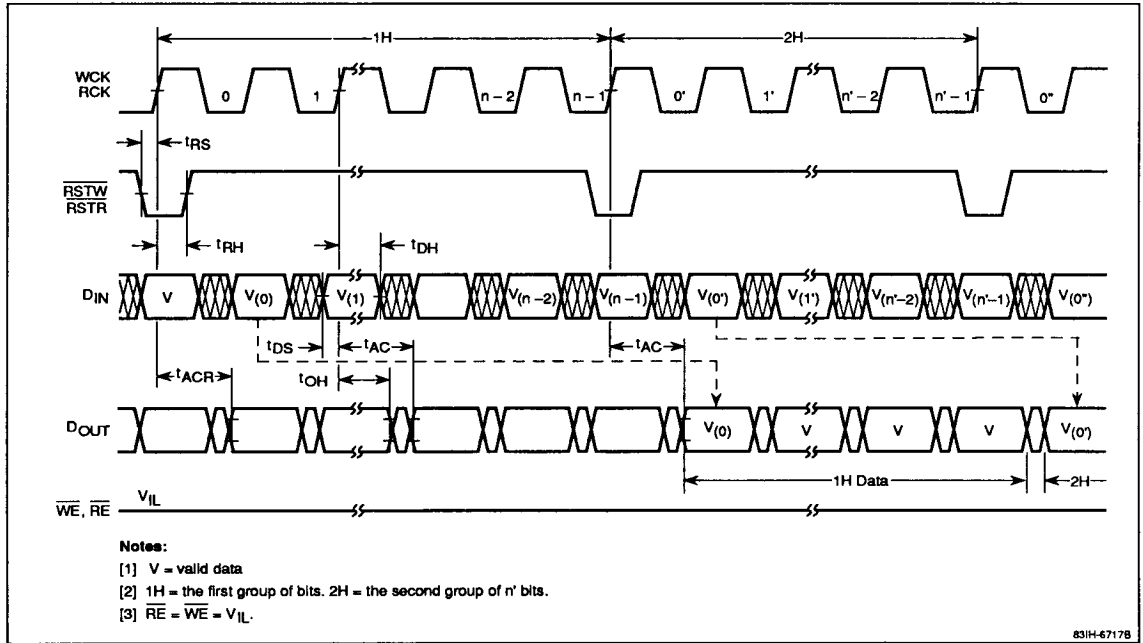
Timing Waveforms (cont)

5048-Bit Delay Line Cycle



Timing Waveforms (cont)

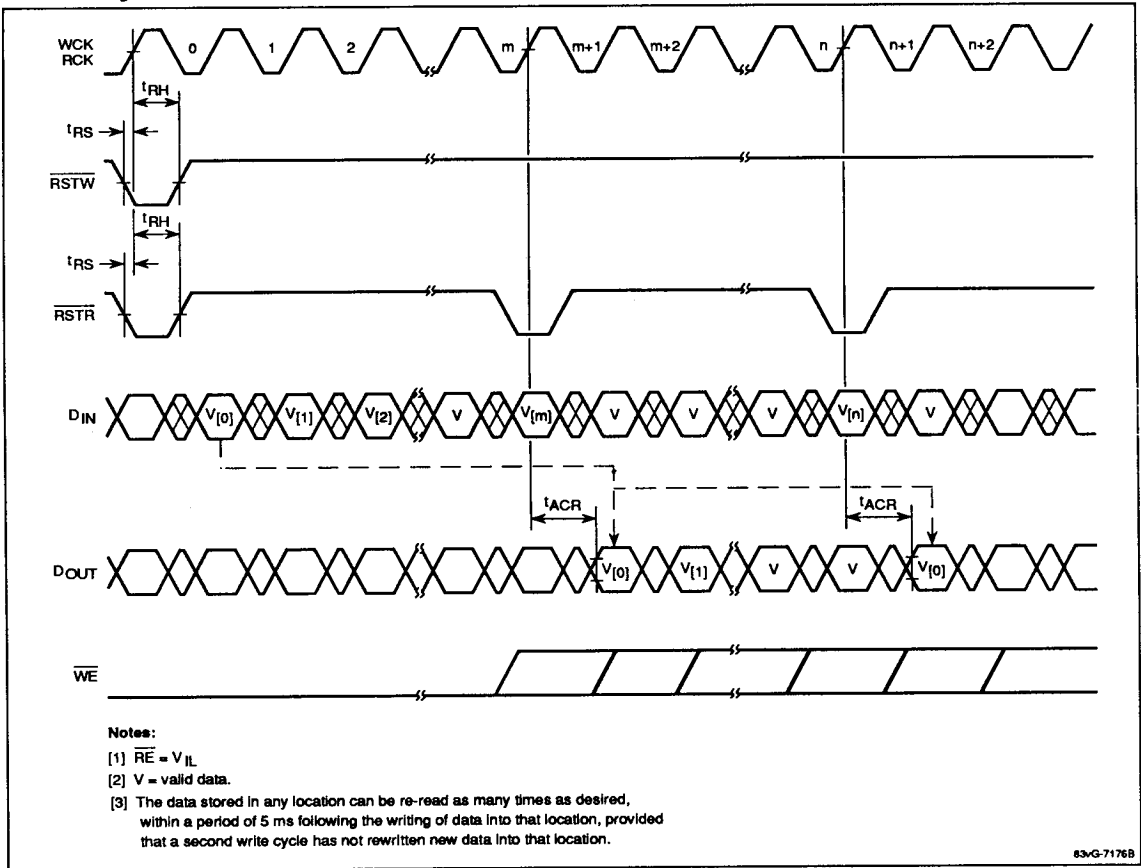
n-Bit Delay Line Cycle



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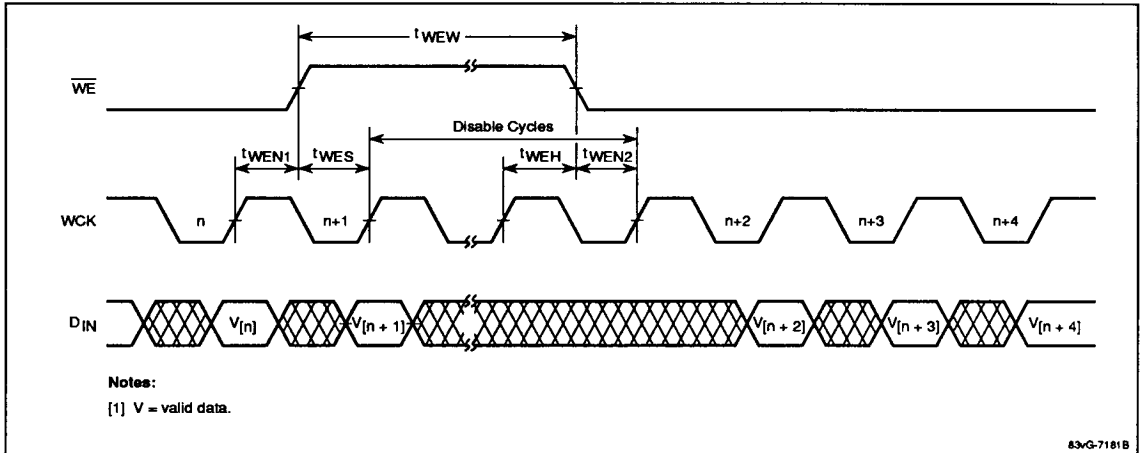
Timing Waveforms (cont)

Re-Read Cycle



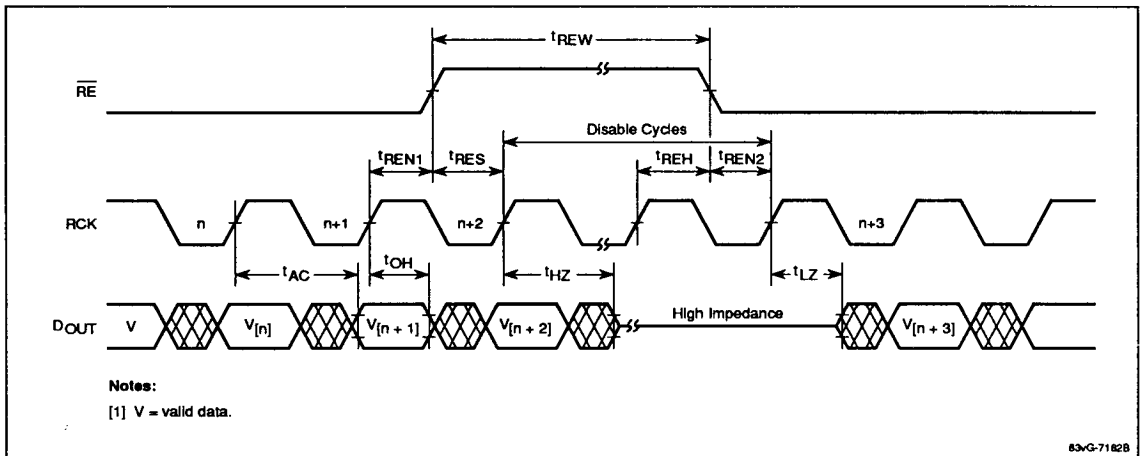
Timing Waveforms (cont)

Write Disable Cycle



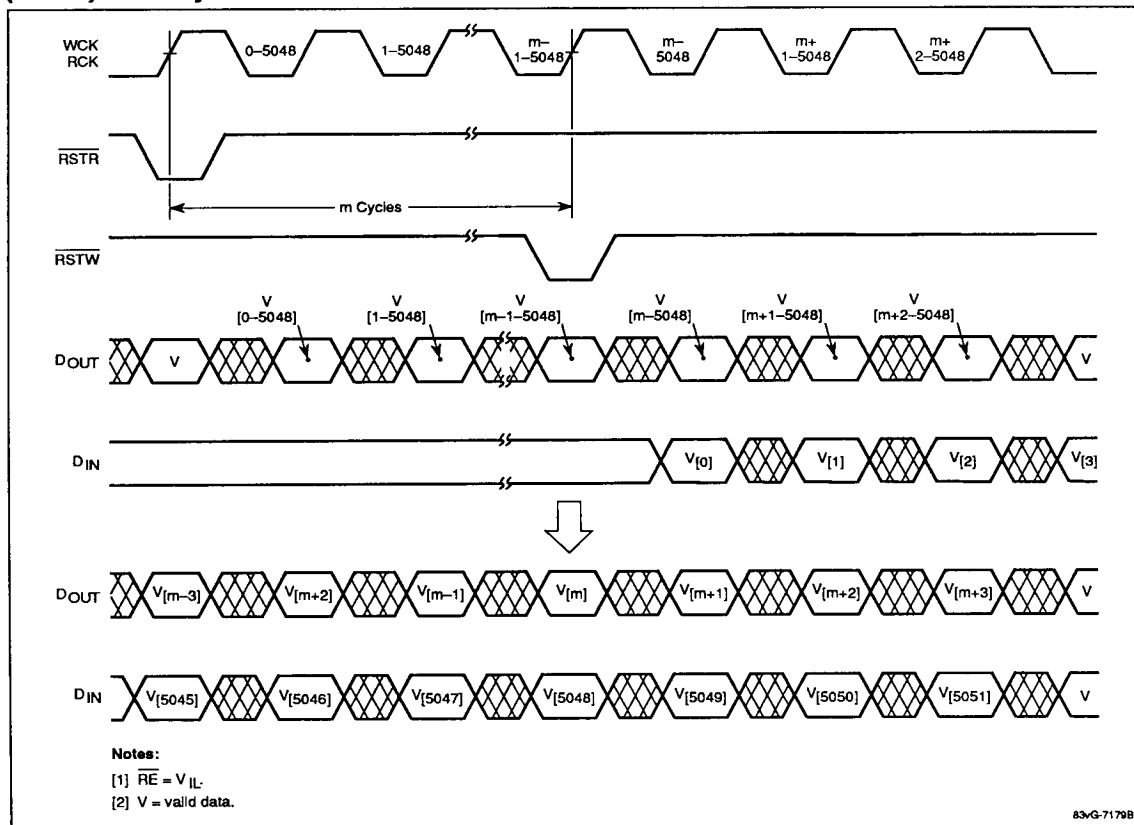
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Read Disable Cycle



Timing Waveforms (cont)

(5048-m)-Bit Delay Line No. 1



Timing Waveforms (cont)

(5048-m)-Bit Delay Line No. 2

